

# Emergence of Top-Down strategies from Bottom-Up Attentional Processes

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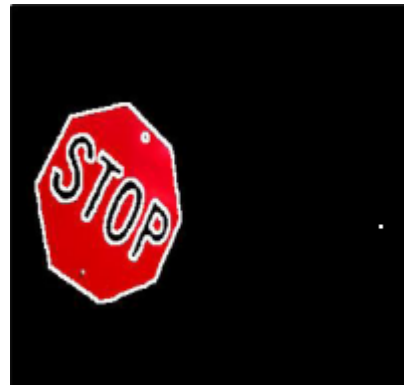
# Overview

- ❖ **Attention in Nutshell**
- ❖ **Application**
- ❖ **Research Challenges Involved**
- ❖ **Motivation of the Research**
- ❖ **Deliverables**
- ❖ **Current Research**
- ❖ **and Results so far....**

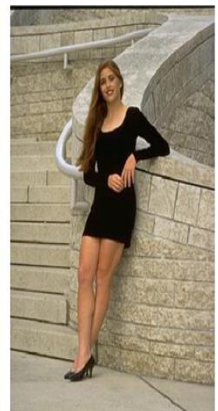
# Attention in Nutshell

- ❖ Attention enables us to allocate limited perceptual and cognitive resources to task-relevant input.
- ❖ Attention spans across modalities like Audio, Vision and other Sensory Inputs.
- ❖ Attention is again sub-classified into two types:
  - ❖ Bottom-Up Attention-which is stimulus driven
  - ❖ Top-Down Attention-which is goal driven

# Illustrations for the applications of Computational Models of Attention



**Salient Region Detection**

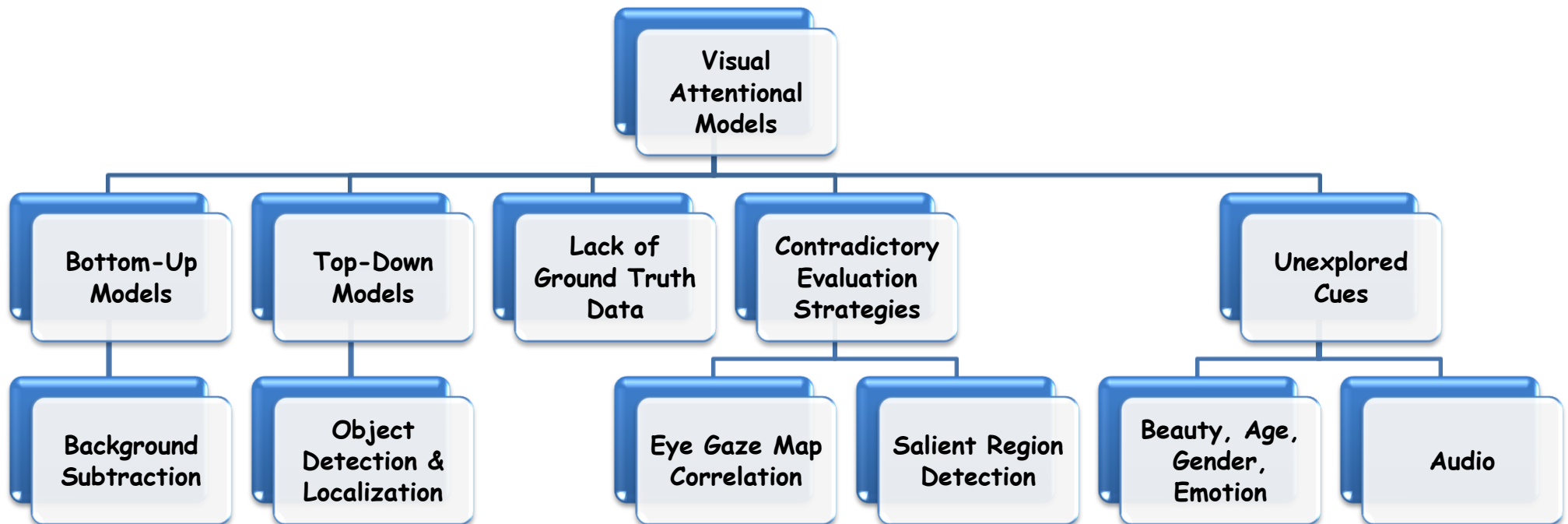


**Object Detection and Localization**

# Applications of Computational Models of Attention

- ❖ **Salient Region Detection**
- ❖ **Seam Carving**
- ❖ **Video Summarization**
- ❖ **Object Detection and Recognition**
- ❖ **Robot Eye Gaze Focusing**
- ❖ **Robot learning and interaction**
- ❖ **Image Compression and Quality Assessment**

# Current Issues and Implementation Bottlenecks



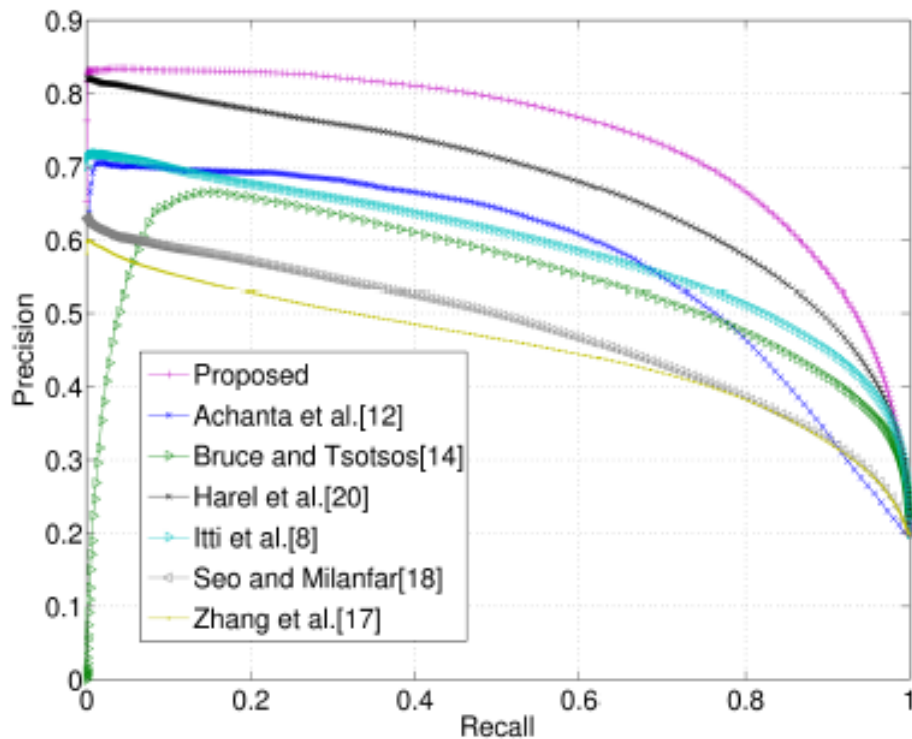
## Motivation of this Research

- ❖ **Develop novel and efficient Bottom-Up and Top-down Attentional Models for Humanoid Robots**
- ❖ **Interaction through cognition, and not merely treated as a computer vision problem**
- ❖ **Propose Score Fusion Techniques for Bottom-Up and Top-Down model combination**
- ❖ **Evaluate the influence of various cues on Robot Learning and Interaction**

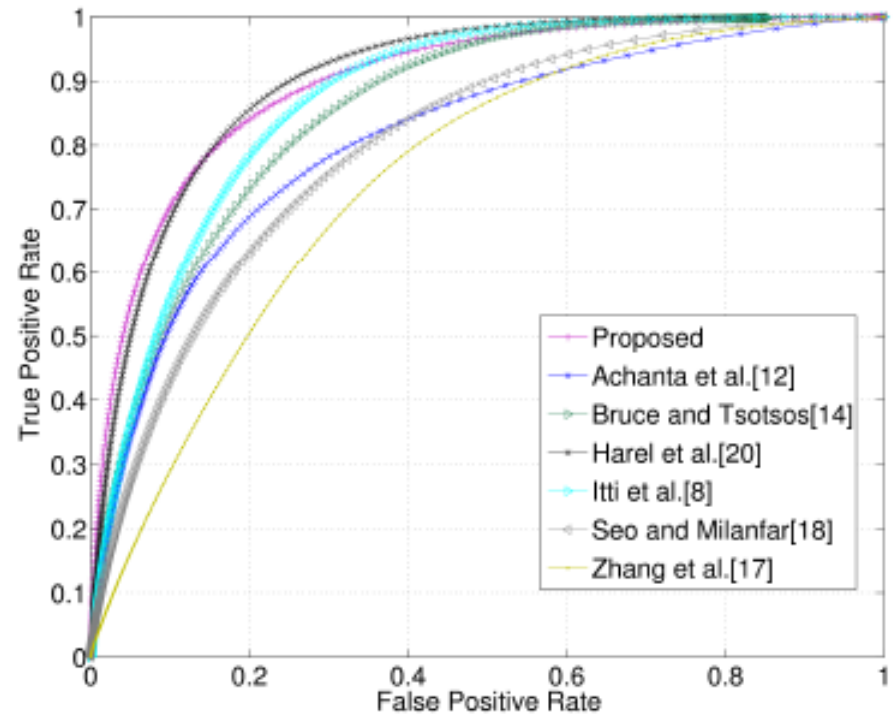
# Work Carried Out So Far



# Results on Microsoft Research Dataset by the Proposed Bottom-Up Attentional Model

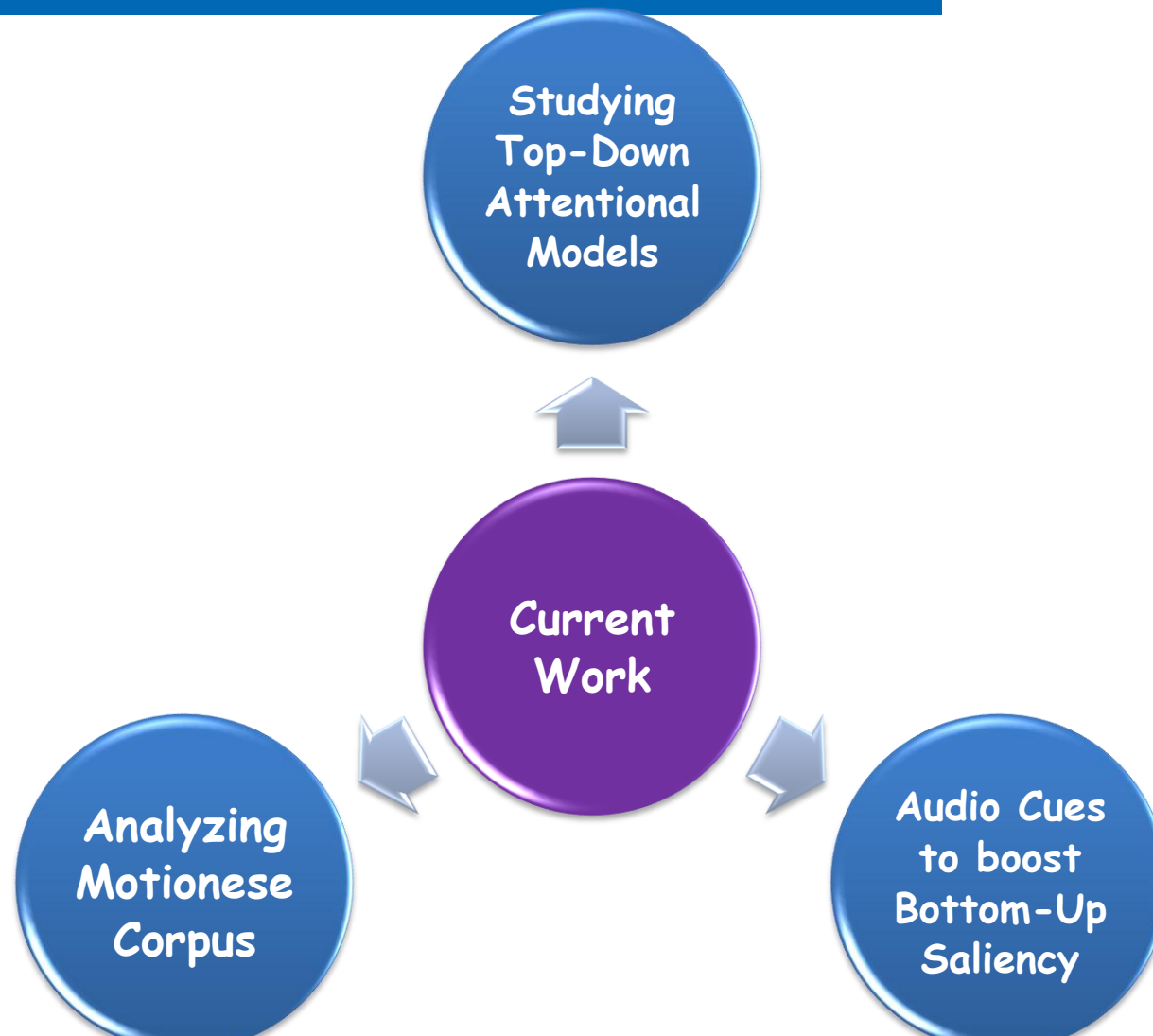


**P/R Plot**

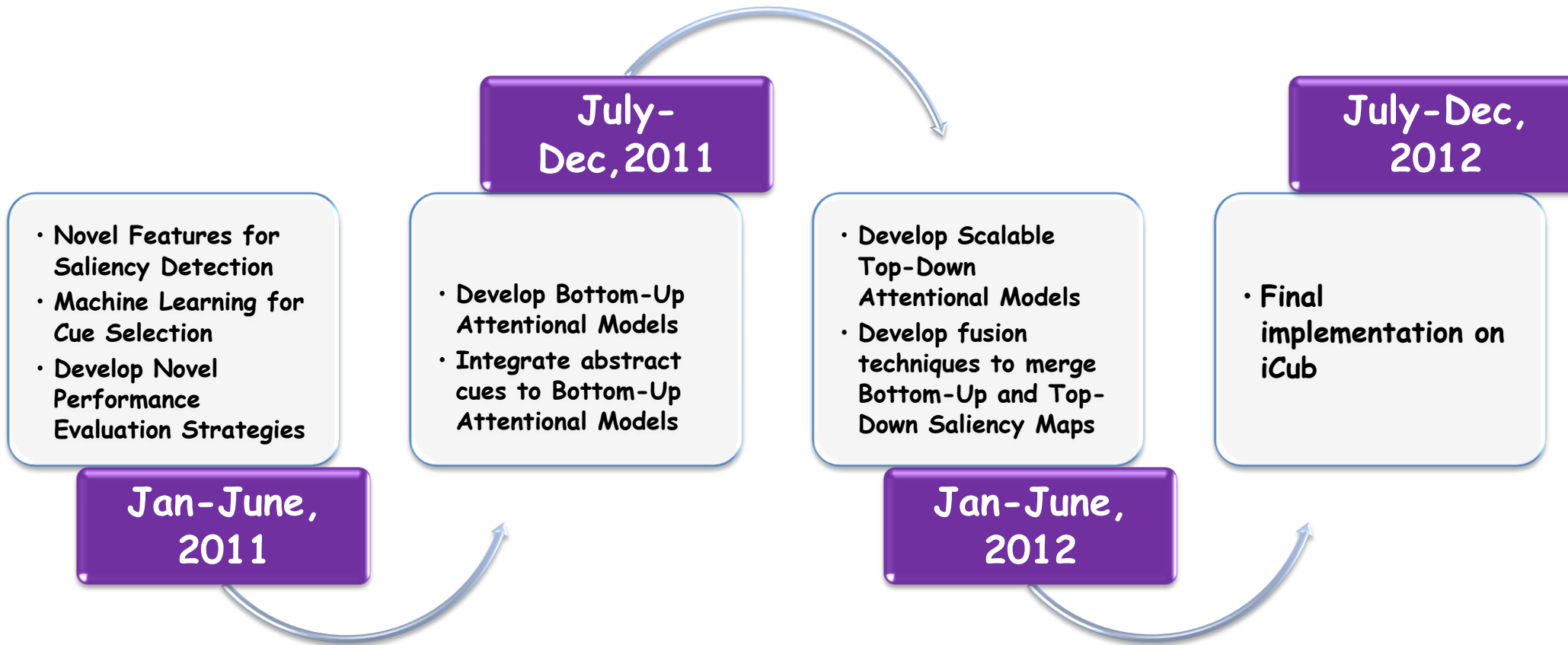


**ROC Plot**

# Current Work



# Future Work with Approximate Time Estimations



## Results and Questions

**Vikram T.N., Marko Tscherepanow and Britta Wrede.  
A Random Center Surround Bottom up Visual Attention  
Model useful for Salient Region Detection. Proceedings  
of IEEE Workshop on Applications of Computer Vision,  
Jan 5-7, 2011. Kona, USA**