

FEEL & WANT node

Cognition & Interaction Lab

The logo for RobotDoc is centered within a dark gray rectangular box. The text "RobotDoc" is rendered in a white, sans-serif font. The letter "D" is stylized, featuring a white graduation cap (mortarboard) on top of its upper curve. A small red dot is positioned on the left side of the "D", just above the baseline of the letters.

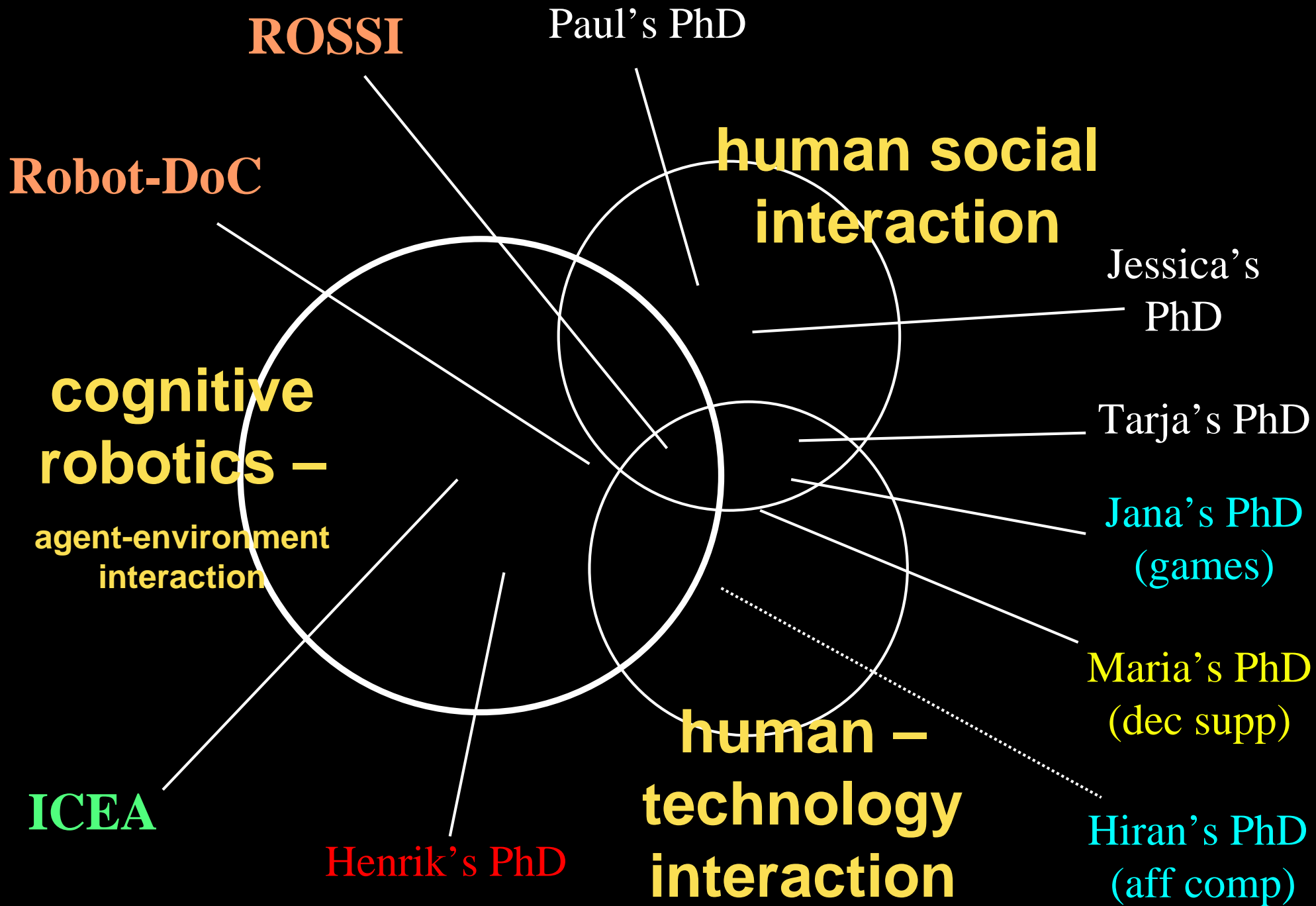
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Embodied Cognition

Our perception of the world, our thoughts, and our social interactions are crucially dependent on our bodies and our **embodied interaction with the world**.

Situated Cognition

Cognition does not (only) take place "in the head", based on internal models of the world, but crucially depends on **active situated interaction with the world**.



Cognition & Interaction Lab

Professor(s)

Tom Ziemke

Assistant professors

Paul Hemeren – ROSSI

Jessica Lindblom

Tarja Susi – IF, comp games

Postdocs

Rob Lowe – ICEA, RobotDoC

Serge Thill – ROSSI

Boris Duran – ROSSI

Research engineers

Pierre Philippe – ICEA

Filippo Saglimbeni – ICEA

PhD students

Henrik Svensson – ICEA

Jana Rambusch – comp games

Maria Nilsson – IF

Alberto Montebelli – ICEA

Malin Aktius – ROSSI

Hiran Ekanayake – aff comp

new X – RoboDOC

new Y – RoboDOC

ICEA

European FP6 project

2006 – 2009, 8.1 M€

10 labs, 7 countries,

40+ people

neurophysiologists

brain modellers

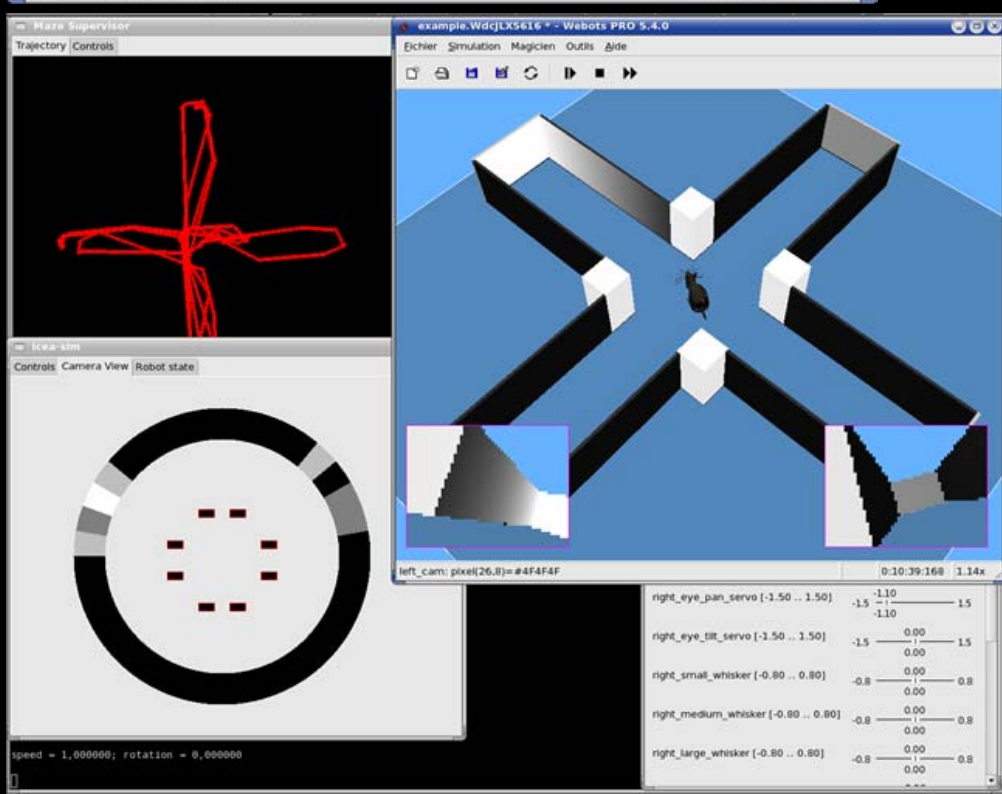
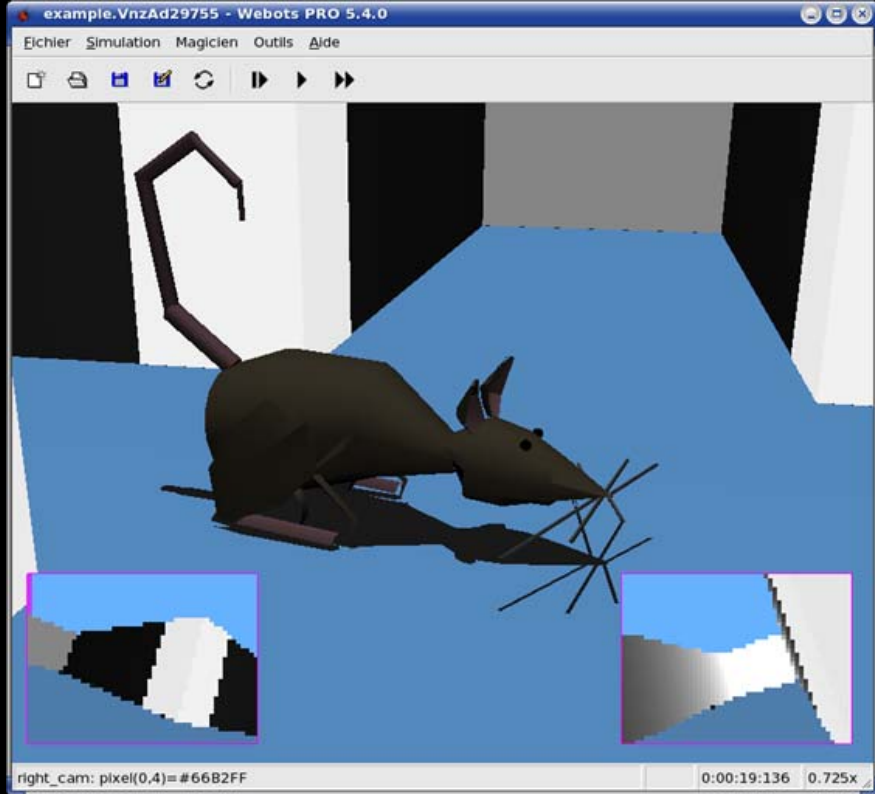
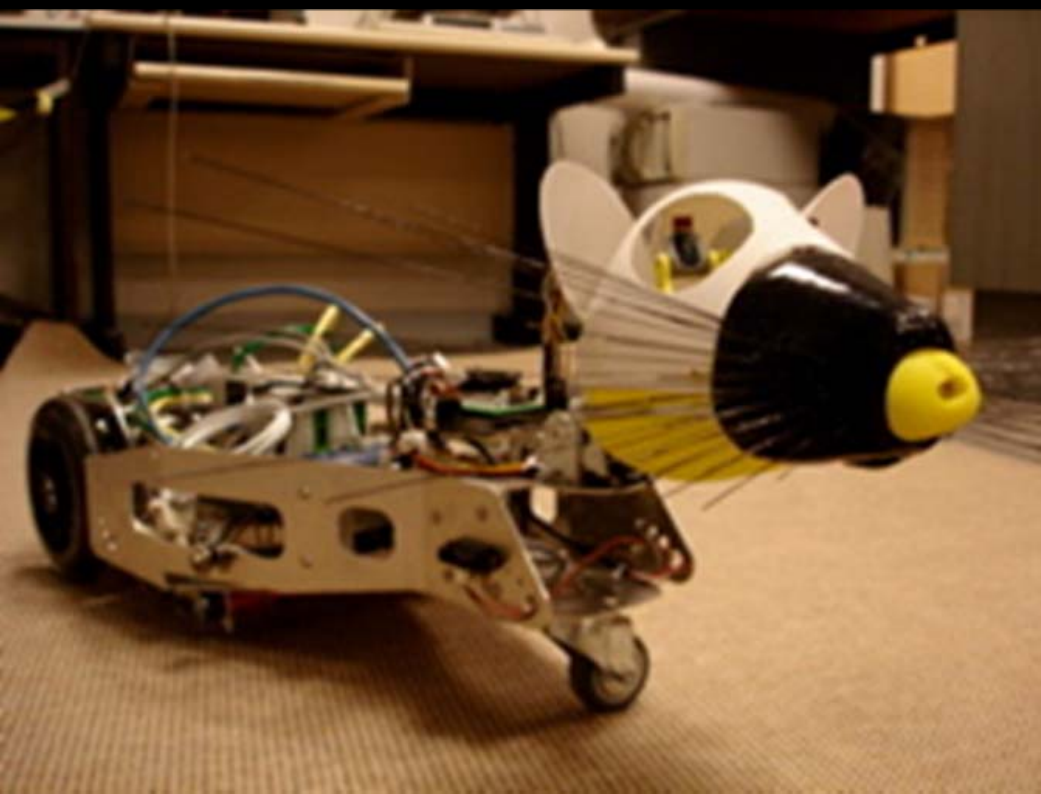
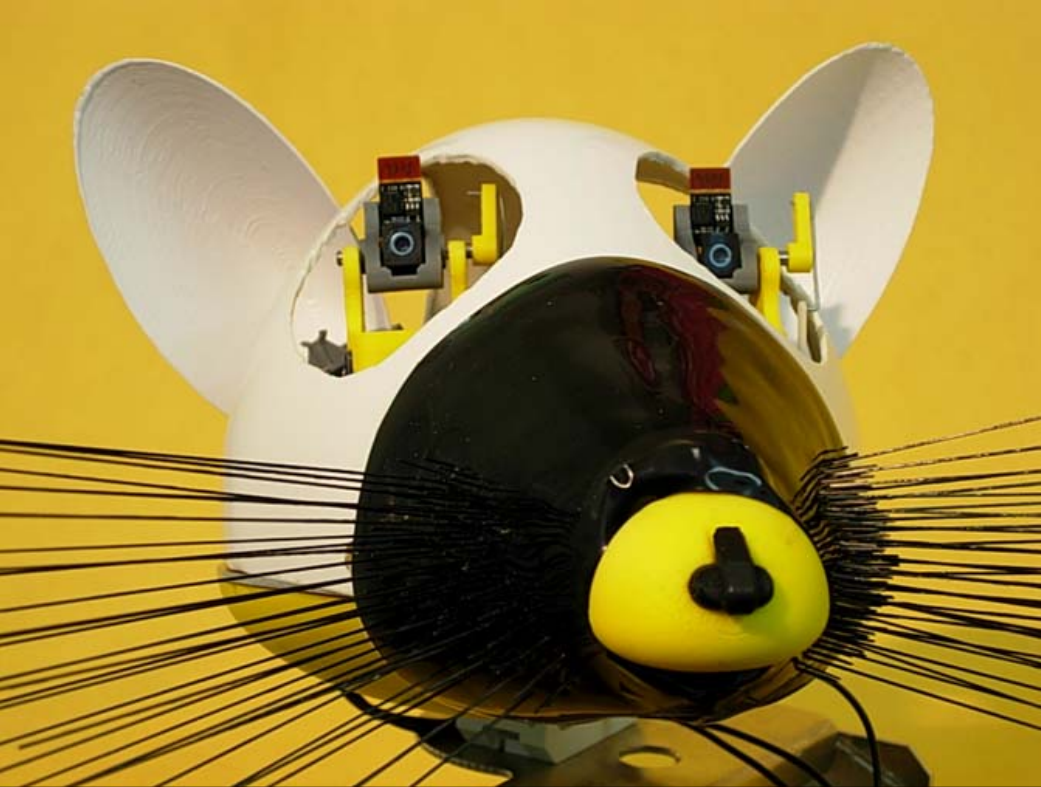
cognitive modellers

roboticists

control engineers

www.iceaproject.eu





Integrating Cognition, Emotion & Autonomy

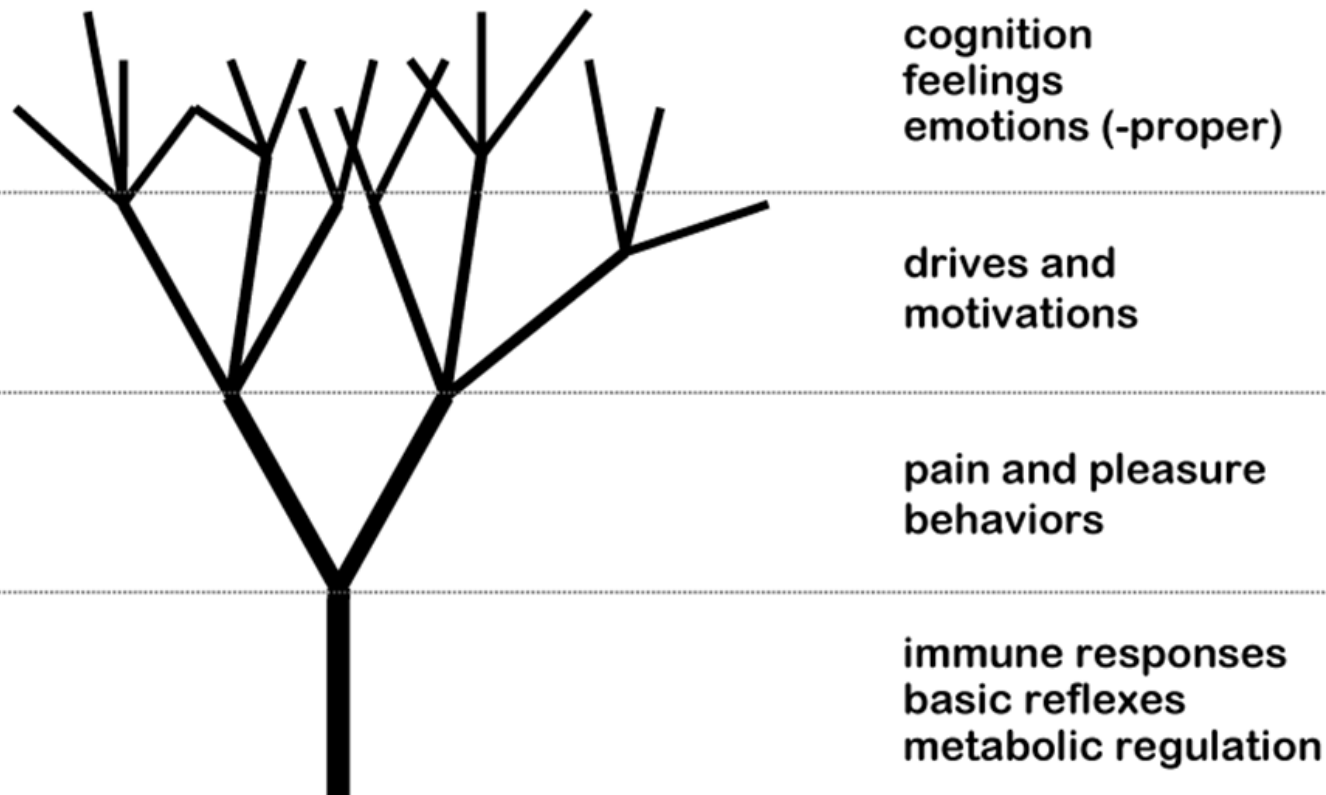
“A key hypothesis ... is that **emotional and homeostatic/autonomic mechanisms** play a critical role in **structuring the high-level thought processes** of living cognitive systems, and

models of these mechanisms can be usefully integrated in **artificial cognitive systems architectures**, which will constitute a significant step towards **truly autonomous cognitive systems** that reason and behave, externally and internally, in accordance with energy and other self-preservation requirements, and thus sustain themselves over extended periods of time.”

[from the proposal]

Cognition & Emotion ...

... according to **somatic theories of emotion** – emerge from **multiple levels of homeostatic bodily self-regulation**



E.g. Damasio:
nature has “**built the apparatus of rationality not just on top of the apparatus of biological regulation, but also from it and with it**”

Why Emotion in Robots?

”Emotions are necessary for the survival of the individual and the species. Therefore, a simple answer to the title of this book [*“Who needs emotions?”*] is that all organisms on earth need emotional systems, in their broadest biological definition.

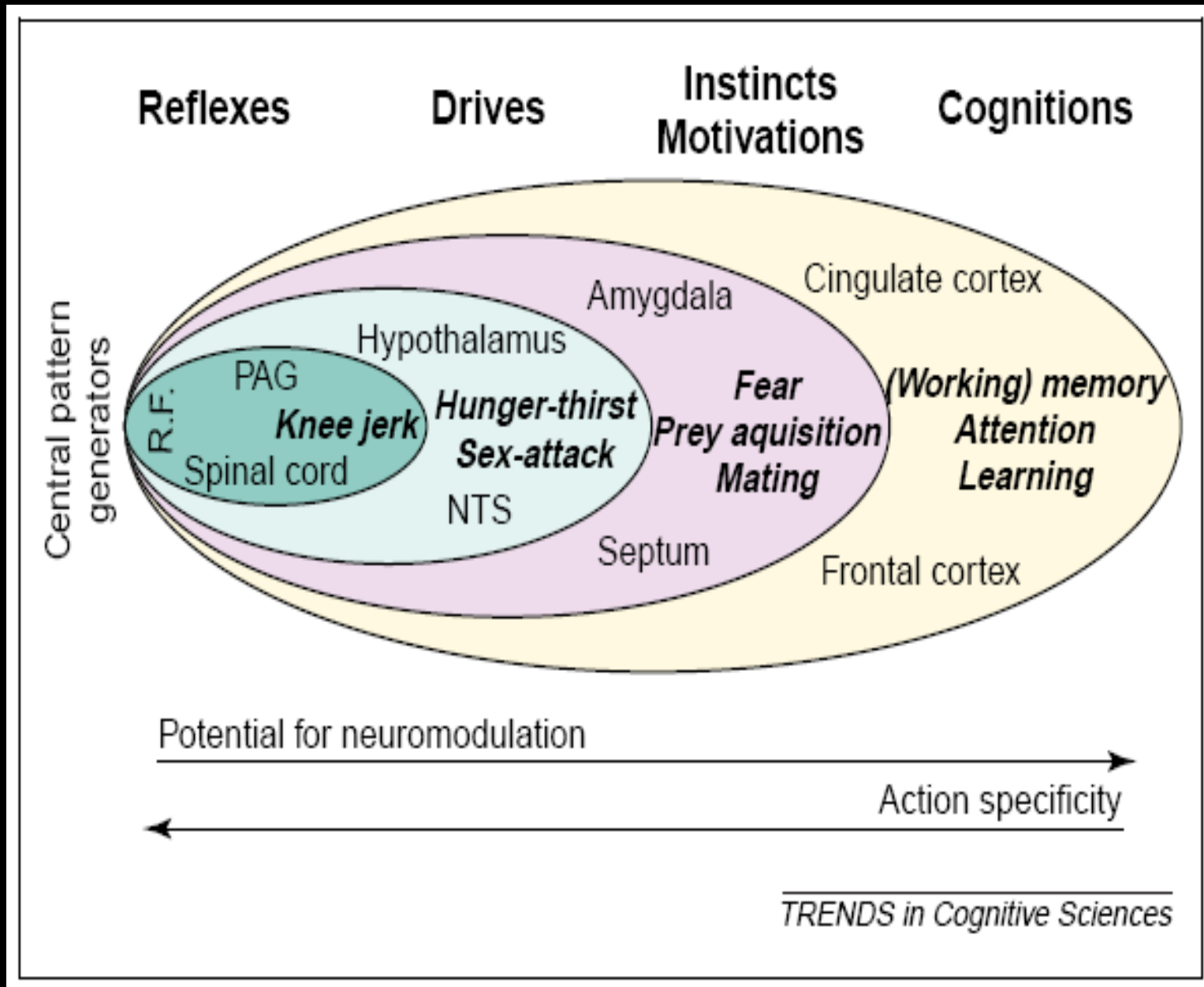
Emotional systems enable animals to more effectively explore and interact with their environment, eat, drink, mate, engage in self-protective and defensive behaviors, and communicate.

Thus, a robot designed to survive in the world as successfully as its living counterparts undoubtedly would require an equivalent system, one that instills urgency to its actions and decisions – in short, one that motivates and directs.”

Kelley (2005, p. 30)

Emotion & Neuromodulation

Arbib & Fellous (2004). *Trends in Cognitive Sciences*.

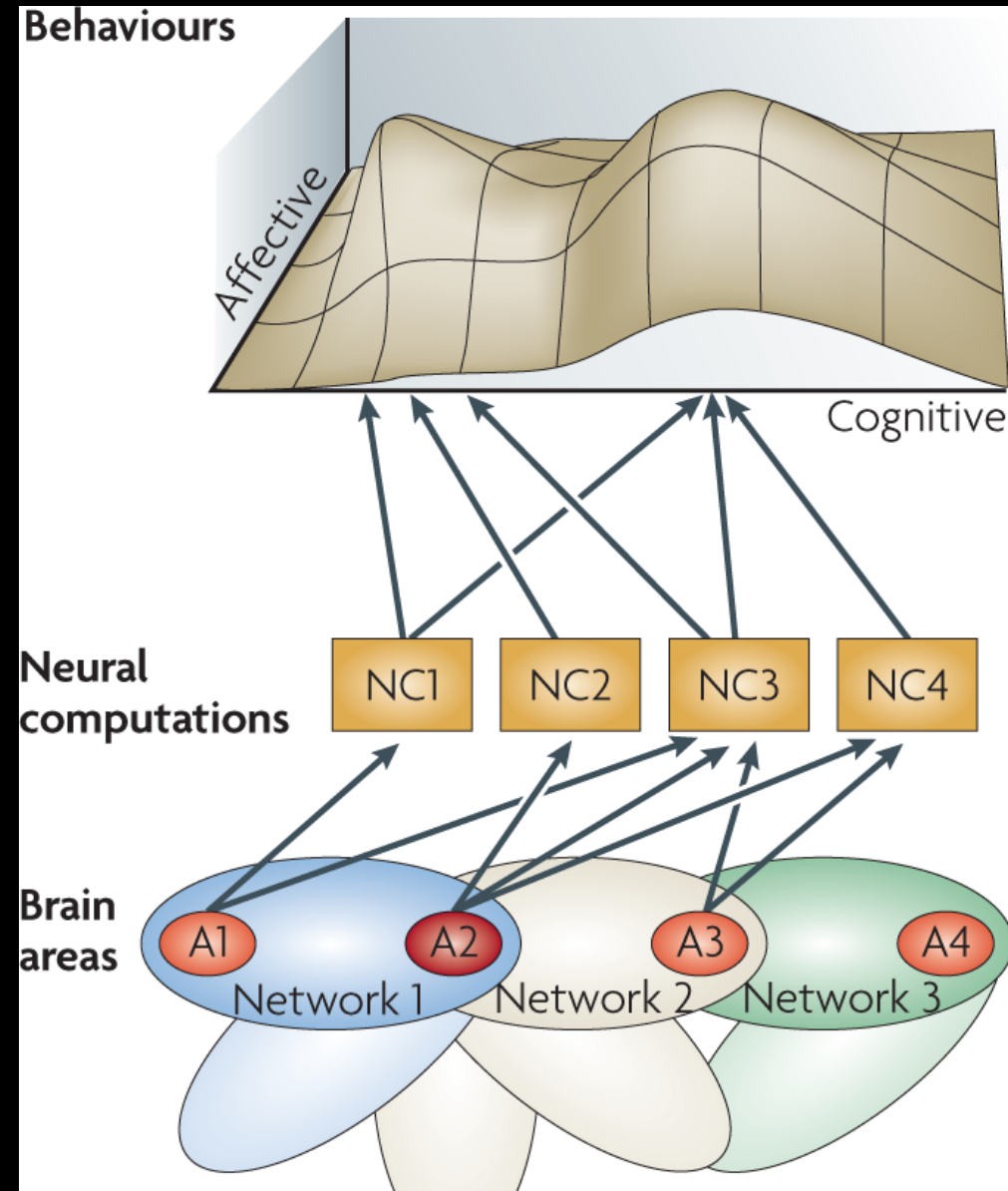


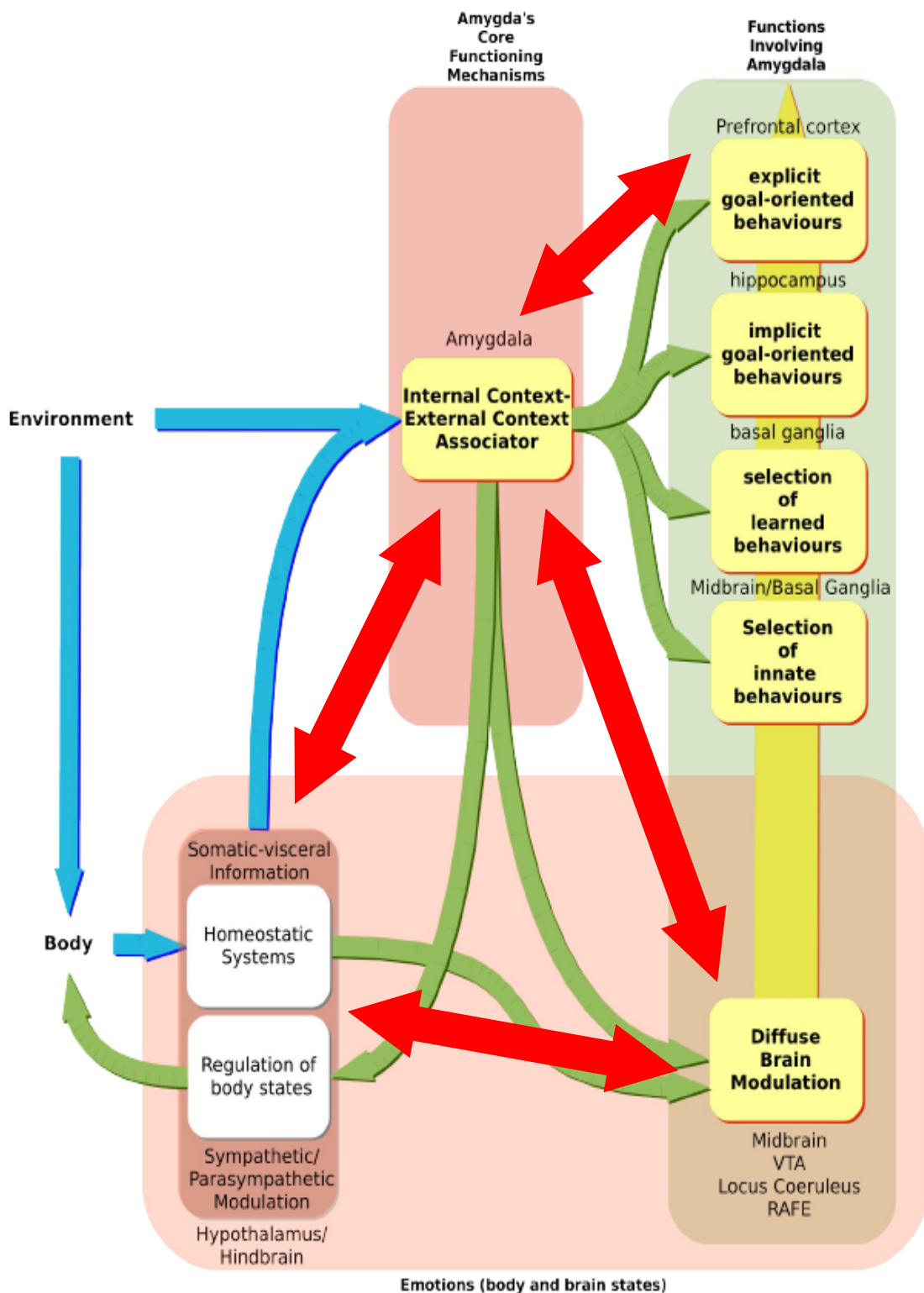
Emotion & Cognition

Pessoa (2008). *Nature Rev Neurosci*, 9(2):148-157.

“... complex cognitive-emotional behaviors have their basis in dynamic coalitions of **networks of brain areas**, none of which should be conceptualized as either ‘affective’ or ‘cognitive’.

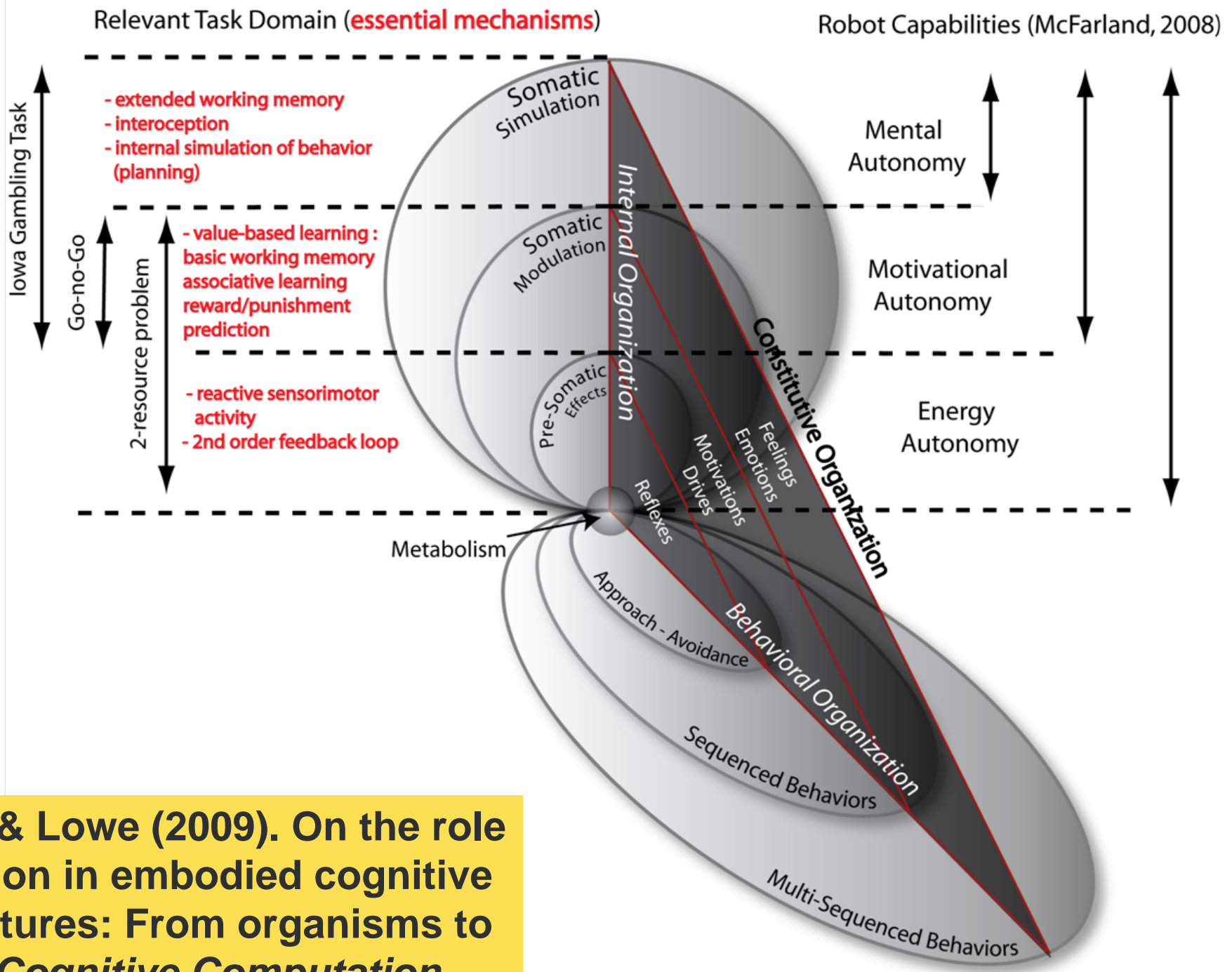
Central to cognitive emotional interactions are brain areas with a high degree of connectivity, called **hubs**, which are critical for regulating the flow and integration between regions.”





ICEA focus in Skövde:

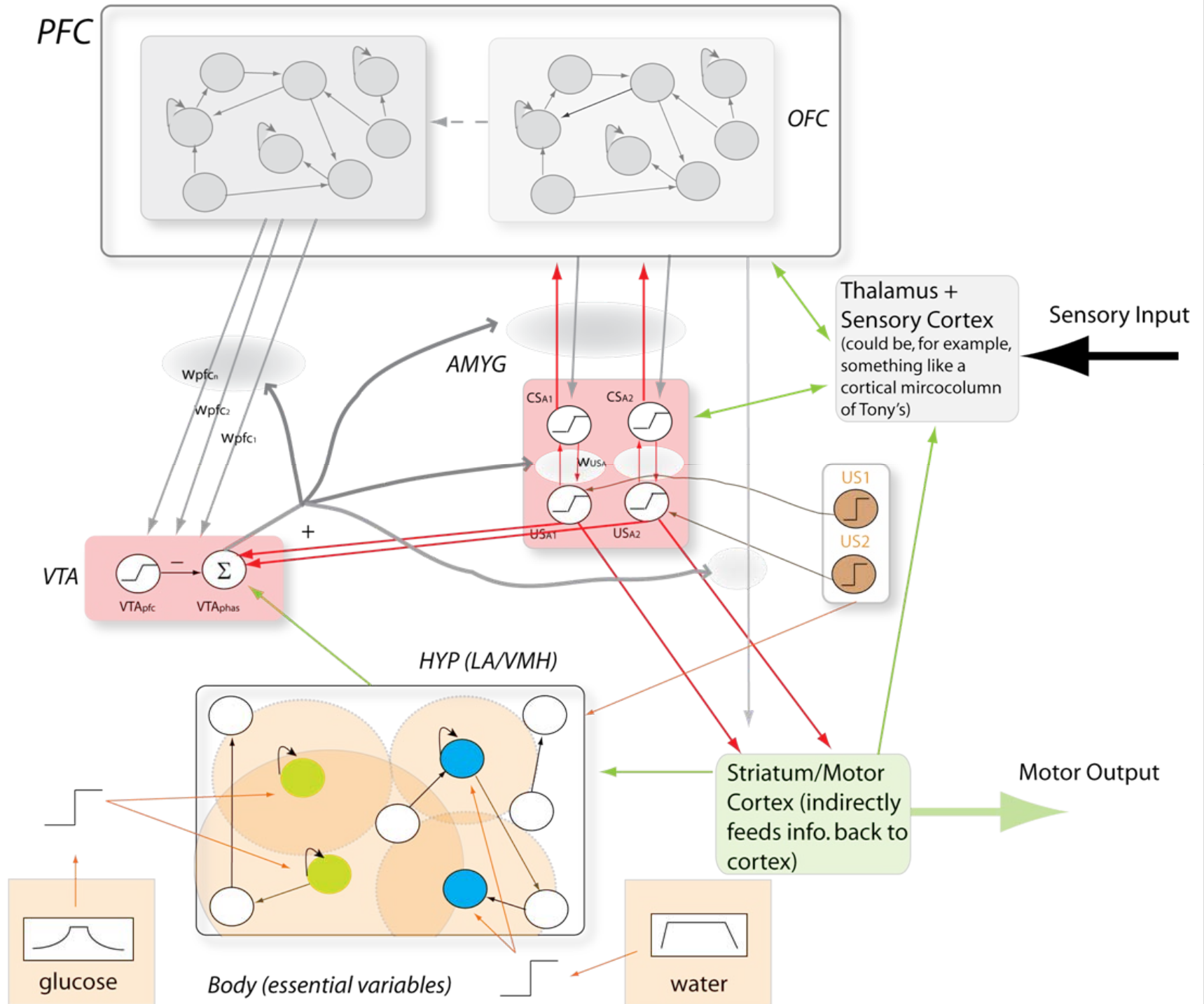
Modeling the interaction of mechanisms at different levels in a neuro-computational cognitive-affective architecture



Ziemke & Lowe (2009). On the role of emotion in embodied cognitive architectures: From organisms to robots. *Cognitive Computation*, 1(1), 104-117.

Fully Integrated Architecture: Reward Based Model of 'Wanting' -

abstractly related to a corticostriatal-hypothalamic-brainstem network (see Kelley & Berridge, 2002)



ROSSI

emergence of communication in RObots through Sensorimotor and Social Interaction

3-year FP7 EU project, March 2008
to February 2011, involving six labs:

cognitive neuroscience

Parma, Lübeck

experimental psychology

Bologna (coord.)

neurocomputational modeling

Skövde

robotics

Ankara, Aberystwyth

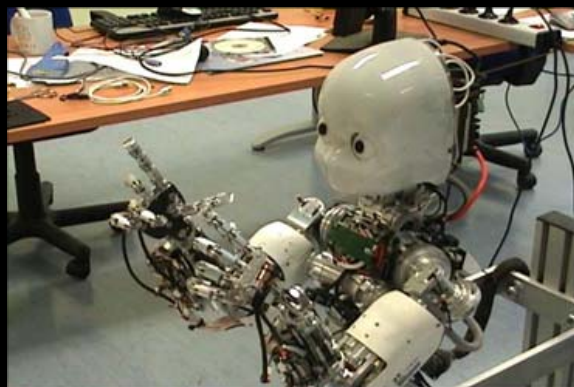


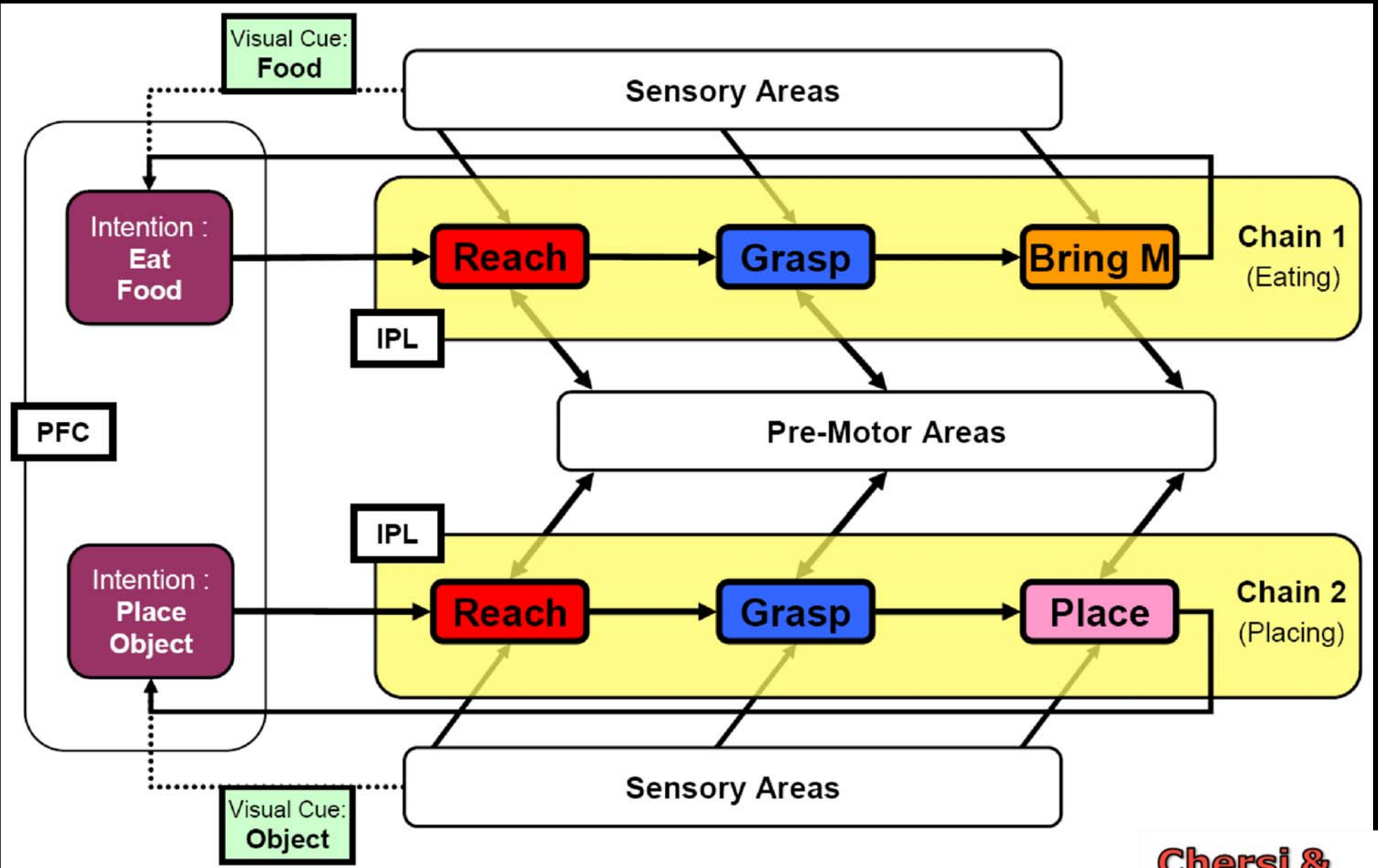
ROSSI - Aims

The main aims of the project are:

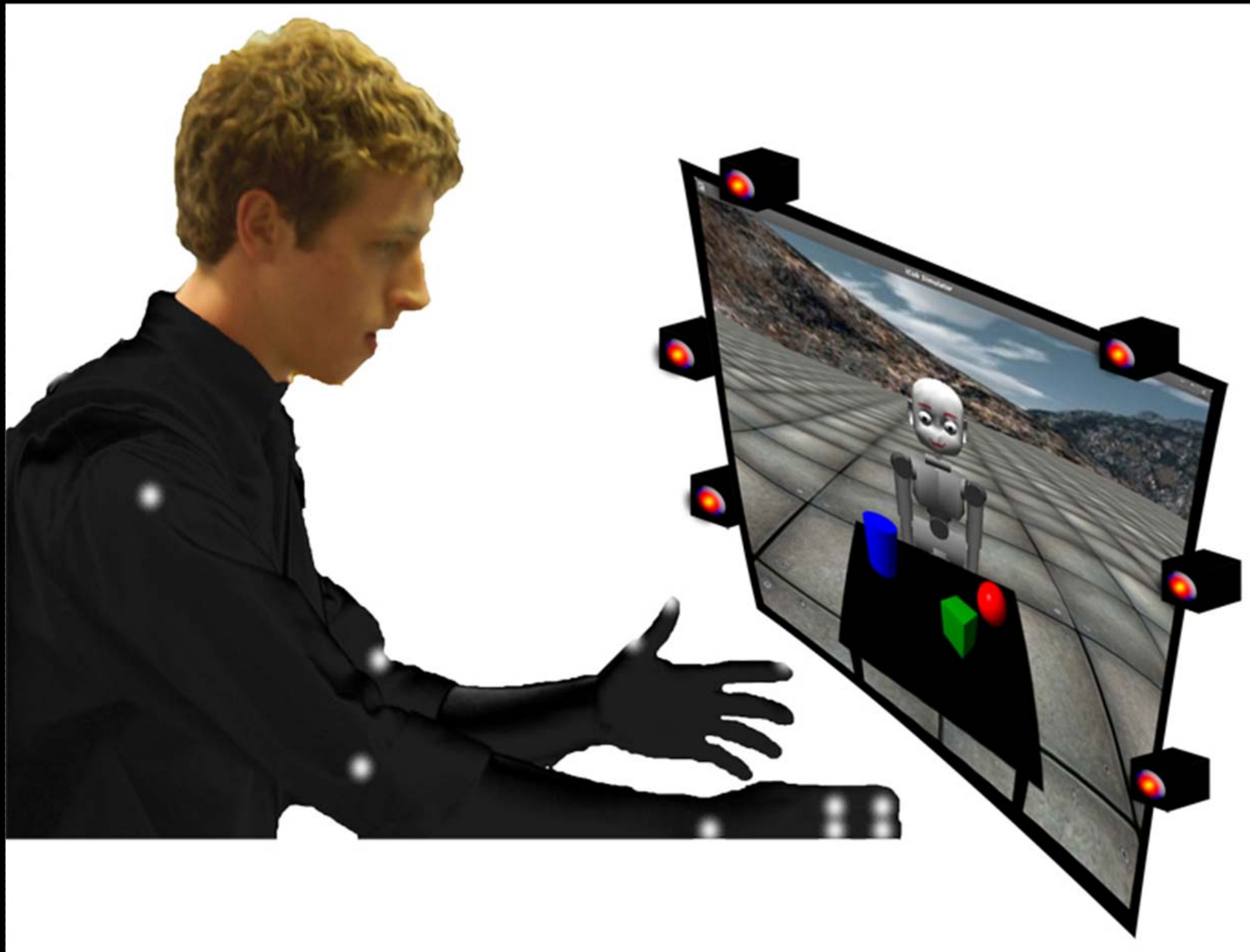
- to provide new **neuroscientific & psychological insights into the sensorimotor grounding of human conceptualization and language use**, in particular the role of canonical and mirror neurons as underlying the use of nouns and verbs,
- to develop **novel approaches to sensorimotor grounding of robotic conceptualization and language use** (more precisely, verbal labeling of objects and actions), based on the insights gained under (a) and richer computational & robotic models of the underlying neural mechanisms.

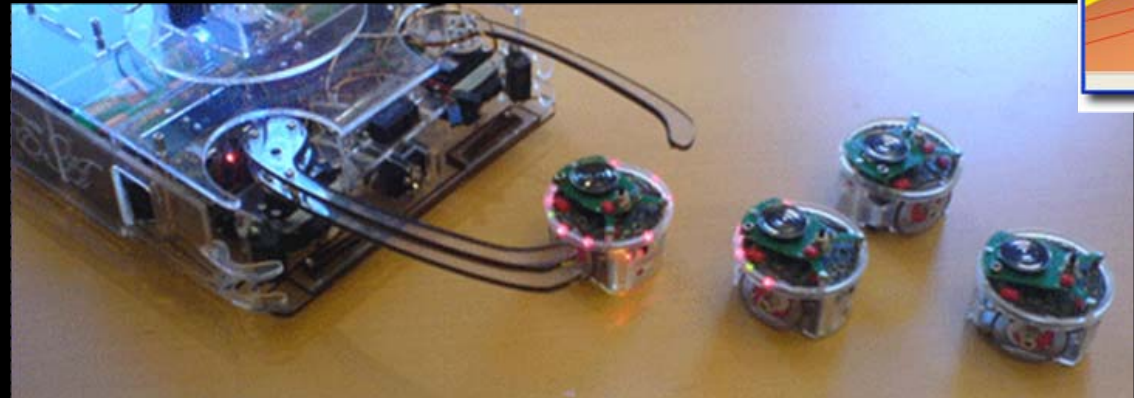
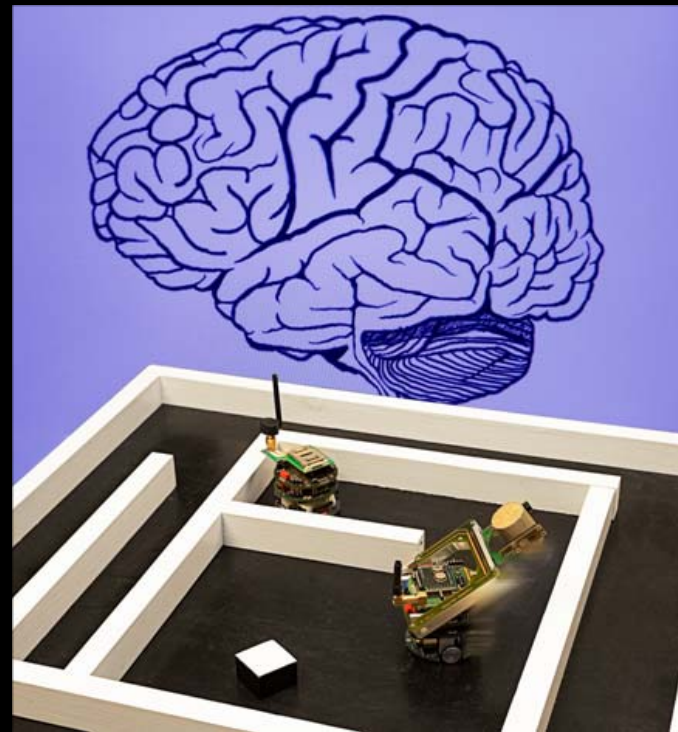
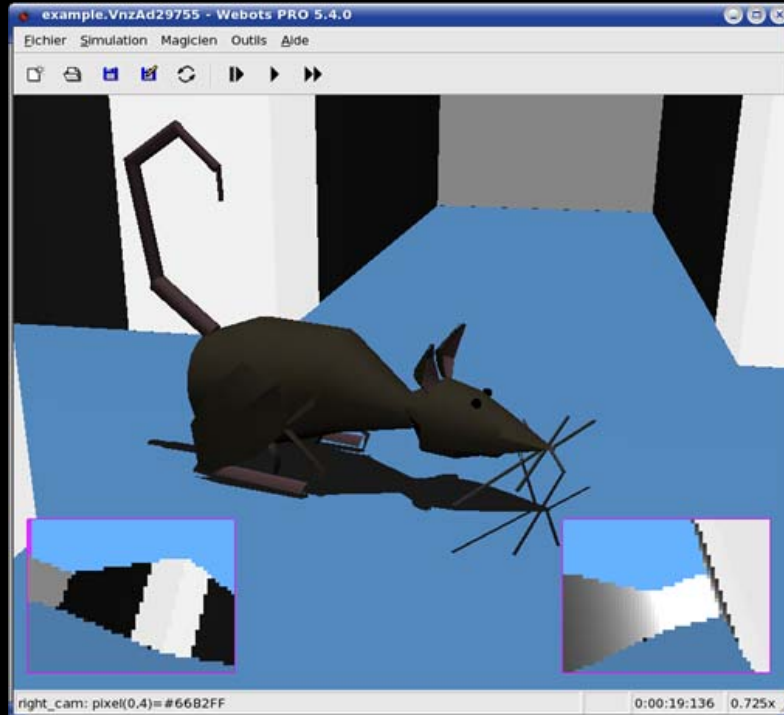
Robot platforms in ROSSI





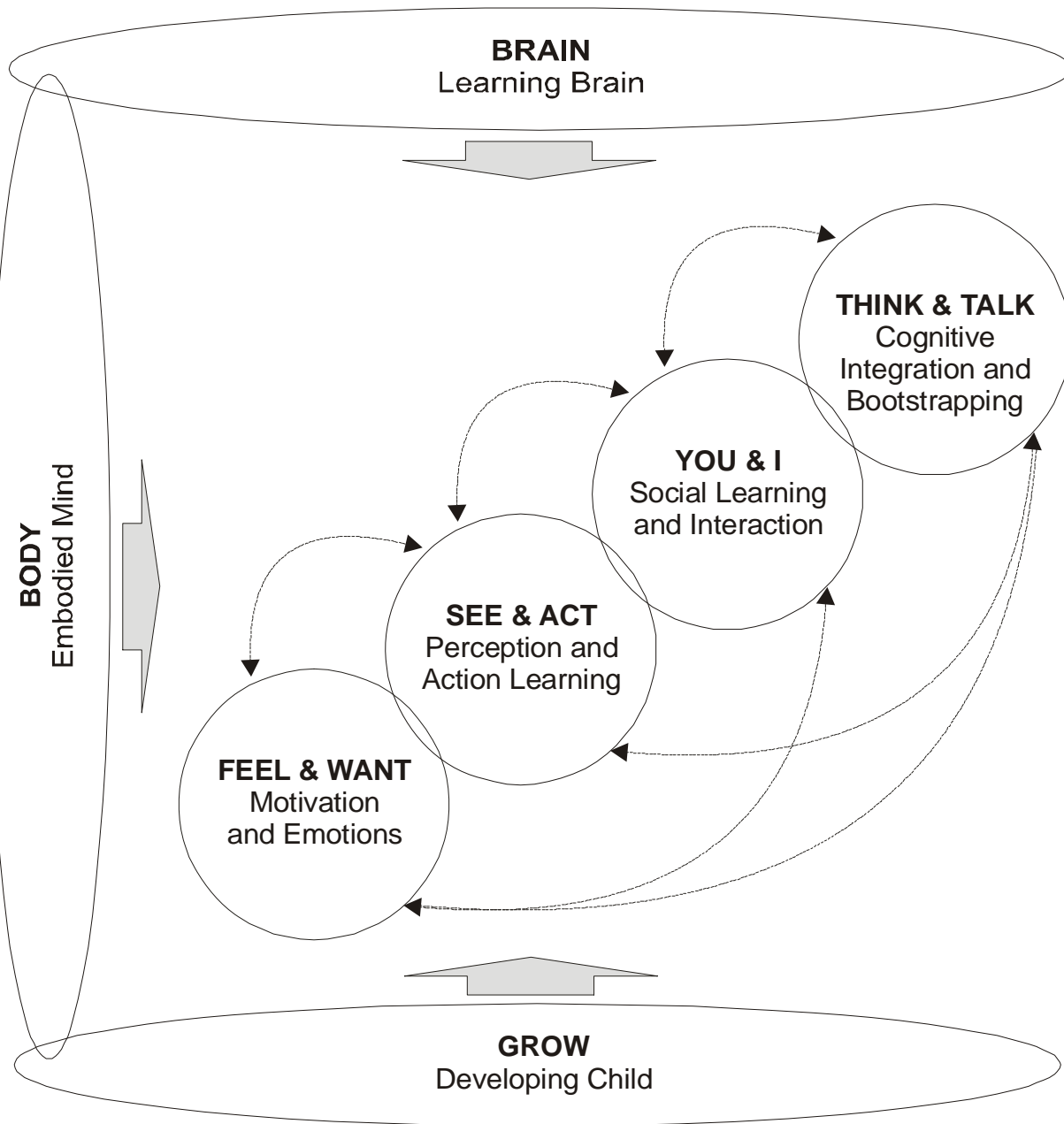
Chersi & colleagues





Cognitive Complexity

Developmental Time



Motivation and Emotions

- *leader node: FEEL&WANT; collaborating nodes: BRAIN, BODY, THINK&TALK*
- Emotion plays a crucial role in rational decision-making and they play a crucial role in coordinating the interactions of different brain systems and different levels of cognitive processing.
- The Collegium will further our understanding of the role of affective mechanisms in cognition through novel developmental robotics investigations.
- The Fellows' research projects in this area will be:
 - **Affective 'representation' and anticipation.** (ESR7 Task 4.1)
 - **Affective modulation of embodied cognition.** (ESR8 Task 4.2)

Task 4.1 - Affective

'representation' and anticipation

- *Fellow ESR7; leader SKOVDE*
- *collaborators PLYMOUTH*
- *Inspired by Damasio's notion of "feelings" as "brain representations" of emotional bodily states and Grush's emulation theory of representation, the following questions will be investigated, a.o.:*
- *How can an embodied agent make use of its perception/interoception of own body-internal/homeostatic states (in addition to perception of the external environment) in structuring its cognition and behaviour? In particular, how can embodied simulation/ anticipation of both sensorimotor and affective consequences of actions interact in the preparation and planning of action (possibly at different levels of abstraction)?*

Task 4.2 Affective modulation of embodied cognition

- *Fellow ESR8; leader SKOVDE*
- *collaborators SUNDERLAND, PLYMOUTH*
- *This research will expand on the ICEA project's cognitive-affective architecture involving different levels of homeostatic regulation in embodied cognitive agents, based on neurocomputational models of the interaction of different mammalian brain structures. While the work in ICEA has been based mainly on models of rat behaviour, the new research will be adapted to the more complex iCub humanoid platform as well as more human-like cognition and behaviour. Questions include:*
- *How can (higher levels of) cognition be grounded in and informed by affective mechanisms? In particular, how can decisionmaking/action selection be based on so-called somatic-markers. How do the time scales of processes at different levels interact?*